## Lecture No 30 Topic: Inverse Transformations

These are also called as opposite transformations. If T is a translation matrix than inverse translation is representing using $\mathrm{T}^{-1}$. The inverse matrix is achieved using the opposite sign.

Translation matrix
$\left(\begin{array}{llll}1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ T_{x} & T_{y} & T_{z} & 1\end{array}\right)$

Inverse translation matrix
$\left(\begin{array}{cccc}1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -T_{x} & -T_{y} & -T_{z} & 1\end{array}\right)$

## Reflection

It is also called a mirror image of an object. For this reflection axis and reflection of plane is selected. Three-dimensional reflections are similar to two dimensions. Reflection is $180^{\circ}$ about the given axis. For reflection, plane is selected ( $x y, x z$ or $y z$ ). Following matrices show reflection respect to all these three planes.
Reflection relative to XY plane


Reflection relative to $Y Z$ plane


$$
\text { Reflection relative to } \mathrm{ZX} \text { plane }
$$

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## Shearing

- It is change in the shape of the object. It is also called as deformation. Change can be in the $x$-direction or $y$-direction or both directions in case of 2D. If shear occurs in both directions, the object will be distorted. But in 3D shear can occur in three directions.

Matrix for shear





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## Lecture No 31 Topic: Curves and Surfaces:

1. Quadric surfaces
2. 2. Spheres
1. 3. Ellipsoid
1. 4. Blobby objects
1. 5. Introductory concepts of Spline
1. 6. Bspline and Bezier curves and surfaces.
